

III. TENSOR METRIC. NOTIUNE DE TENSOR.
TRANSFORMAREA COMPONENTELOR TENSORIALE.
TENSORI DE RANGURILE I ȘI II

1. Demonstrați că energia cinetică a unui corp solid, ce are un punct fix și se mișcă cu viteza unghiulară momentană $\vec{\omega}$, este

$$T = \frac{1}{2} \vec{\omega}^T I_{\text{oo0}},$$

I_{oo0} - momentul de inerție al corpului față de axa de rotație.

Rezolvare:

Energia cinetică:

$$T = \frac{1}{2} \sum_{n=1}^N m_n \vec{V}_n^2, \text{ folosim formulele Euler}$$

$$\vec{V}_n = \vec{\omega} \times \vec{r}_n;$$

$$T = \frac{1}{2} \sum_{n=1}^N m_n (\vec{\omega} \times \vec{r}_n)^2 = \frac{1}{2} \sum_{n=1}^N m_n (\vec{\omega} \times \vec{r}_n) (\vec{\omega} \times \vec{r}_n). \quad (1)$$

Folosim formulele:

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B} \cdot (\vec{A} \cdot \vec{C}) - \vec{C} \cdot (\vec{A} \cdot \vec{B}); \quad (2)$$

$$(\vec{A} \times \vec{B}) \cdot \vec{C} = (\vec{B} \times \vec{C}) \cdot \vec{A} = (\vec{C} \times \vec{A}) \cdot \vec{B};$$

$$T = \frac{1}{2} \sum_{n=1}^N m_n \omega [\vec{r}_n \times (\vec{\omega} \times \vec{r}_n)] = \frac{1}{2} \sum_{n=1}^N m_n \omega [\omega (\vec{r}_n)^2 - \vec{r}_n \cdot (\vec{r}_n \omega)] = \\ = \frac{1}{2} \sum_{n=1}^N m_n [\omega^2 (\vec{r}_n)^2 - (\omega \cdot \vec{r}_n)^2]. \quad (3)$$

Notăm $\vec{\omega}^0 = \frac{\vec{\omega}}{\omega}$ și considerând expresia pentru momentul de inerție (pr.2)

$$I_{mn} = \sum_{n=1}^N m_n \left[x_i^{(n)} x_l^{(n)} - (x_i^{(n)} u_i)^2 \right];$$

$$T = \frac{1}{2} \omega^2 \sum_{n=1}^N m_n \left[\vec{r}_n^2 - (\omega^0 \cdot \vec{r}_n)^2 \right] = \frac{1}{2} \omega^0 \cdot I_{\text{oo0}}$$

I_{oo0} - tensorul momentului de inerție.

2. Aflați expresia pentru momentul de inerție al sistemului punctelor materiale față de axa (u) cu vectorul unitar \vec{u} .
Rezolvare (de sine statător).

3. În sistemul cartezian de coordonate $K(\vec{i}_1, \vec{i}_2, \vec{i}_3)$ sunt date componentele tensorului de rangul doi:

$$\|A^{ik}\| = \|A_i^k\| = \|A_k^i\| = \|A_{ik}\| = \begin{vmatrix} 1 & 3 & 1 \\ 2 & 1 & 3 \\ 1 & 2 & 2 \end{vmatrix}$$

Vectorii de bază ai sistemului de coordonate K' se exprimă ca:

$$\vec{e}_1 = -\vec{i}_1 + \vec{i}_3; \quad \vec{e}_2 = \vec{i}_1 + \vec{i}_2; \quad \vec{e}_3 = \vec{i}_3.$$

Să se afle componentele covariante, contravariante și mixte în sistemul de coordonate K' ($A'^{ik}, A'_{ik}, A'^k_i, A'^i_k, A'^i_k - ?$).
Rezolvare:

Trecerea de la un sistem de coordonate la altul $K' \rightarrow K$ se efectuează conform legii:

$$\vec{e}'_i = \alpha_i^k \vec{e}_k. \quad (1)$$

Deci $A'^{ik} = \alpha_i^m \alpha_k^n A_{mn}$, unde coeficienții α_i^m sunt coeficienții transformării directe pe care-i putem afla din matricea de transformare a bazelor (1):

$$\alpha_i^j = \begin{pmatrix} -1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}. \quad (2)$$

Vom avea:

$$\begin{aligned}
A'_{11} &= \alpha_1^1 \alpha_1^1 A_{11} + \alpha_1^1 \alpha_1^2 A_{12} + \alpha_1^1 \alpha_1^3 A_{13} + \\
&+ \alpha_1^2 \alpha_1^1 A_{21} + \alpha_1^2 \alpha_1^2 A_{22} + \alpha_1^2 \alpha_1^3 A_{23} + \\
&+ \alpha_1^3 \alpha_1^1 A_{31} + \alpha_1^3 \alpha_1^2 A_{32} + \alpha_1^3 \alpha_1^3 A_{33} = 1; \\
A'_{12} &= \alpha_1^1 \alpha_2^1 A_{11} + \alpha_1^1 \alpha_2^2 A_{12} + \alpha_1^1 \alpha_2^3 A_{13} + \\
&+ \alpha_1^2 \alpha_2^1 A_{21} + \alpha_1^2 \alpha_2^2 A_{22} + \alpha_1^2 \alpha_2^3 A_{23} + \\
&+ \alpha_1^3 \alpha_2^1 A_{31} + \alpha_1^3 \alpha_2^2 A_{32} + \alpha_1^3 \alpha_2^3 A_{33} = -1; \\
A'_{13} &= \alpha_1^1 \alpha_3^1 A_{11} + \alpha_1^1 \alpha_3^2 A_{12} + \alpha_1^1 \alpha_3^3 A_{13} + \\
&+ \alpha_1^2 \alpha_3^1 A_{21} + \alpha_1^2 \alpha_3^2 A_{22} + \alpha_1^2 \alpha_3^3 A_{23} + \\
&+ \alpha_1^3 \alpha_3^1 A_{31} + \alpha_1^3 \alpha_3^2 A_{32} + \alpha_1^3 \alpha_3^3 A_{33} = 2; \\
A'_{21} &= \alpha_2^1 \alpha_1^1 A_{11} + \alpha_2^1 \alpha_1^2 A_{12} + \alpha_2^1 \alpha_1^3 A_{13} + \\
&+ \alpha_2^2 \alpha_1^1 A_{21} + \alpha_2^2 \alpha_1^2 A_{22} + \alpha_2^2 \alpha_1^3 A_{23} + \\
&+ \alpha_2^3 \alpha_1^1 A_{31} + \alpha_2^3 \alpha_1^2 A_{32} + \alpha_2^3 \alpha_1^3 A_{33} = -2; \\
A'_{31} &= \alpha_3^1 \alpha_1^1 A_{11} + \alpha_3^1 \alpha_1^2 A_{12} + \alpha_3^1 \alpha_1^3 A_{13} + \\
&+ \alpha_3^2 \alpha_1^1 A_{21} + \alpha_3^2 \alpha_1^2 A_{22} + \alpha_3^2 \alpha_1^3 A_{23} + \\
&+ \alpha_3^3 \alpha_1^1 A_{31} + \alpha_3^3 \alpha_1^2 A_{32} + \alpha_3^3 \alpha_1^3 A_{33} = 1; \\
A'_{22} &= \alpha_2^1 \alpha_2^1 A_{11} + \alpha_2^1 \alpha_2^2 A_{12} + \alpha_2^1 \alpha_2^3 A_{13} + \\
&+ \alpha_2^2 \alpha_2^1 A_{21} + \alpha_2^2 \alpha_2^2 A_{22} + \alpha_2^2 \alpha_2^3 A_{23} + \\
&+ \alpha_2^3 \alpha_2^1 A_{31} + \alpha_2^3 \alpha_2^2 A_{32} + \alpha_2^3 \alpha_2^3 A_{33} = 7;
\end{aligned}$$

$$\begin{aligned}
A'_{23} &= \alpha_2^1 \alpha_3^1 A_{11} + \alpha_2^1 \alpha_3^2 A_{12} + \alpha_2^1 \alpha_3^3 A_{13} + \\
&+ \alpha_2^2 \alpha_3^1 A_{21} + \alpha_2^2 \alpha_3^2 A_{22} + \alpha_2^2 \alpha_3^3 A_{23} + \\
&+ \alpha_2^3 \alpha_3^1 A_{31} + \alpha_2^3 \alpha_3^2 A_{32} + \alpha_2^3 \alpha_3^3 A_{33} = 4; \\
A'_{32} &= \alpha_3^1 \alpha_2^1 A_{11} + \alpha_3^1 \alpha_2^2 A_{12} + \alpha_3^1 \alpha_2^3 A_{13} + \\
&+ \alpha_3^2 \alpha_2^1 A_{21} + \alpha_3^2 \alpha_2^2 A_{22} + \alpha_3^2 \alpha_2^3 A_{23} + \\
&+ \alpha_3^3 \alpha_2^1 A_{31} + \alpha_3^3 \alpha_2^2 A_{32} + \alpha_3^3 \alpha_2^3 A_{33} = 3; \\
A'_{33} &= \alpha_3^1 \alpha_3^1 A_{11} + \alpha_3^1 \alpha_3^2 A_{12} + \alpha_3^1 \alpha_3^3 A_{13} + \\
&+ \alpha_3^2 \alpha_3^1 A_{21} + \alpha_3^2 \alpha_3^2 A_{22} + \alpha_3^2 \alpha_3^3 A_{23} + \\
&+ \alpha_3^3 \alpha_3^1 A_{31} + \alpha_3^3 \alpha_3^2 A_{32} + \alpha_3^3 \alpha_3^3 A_{33} = 2.
\end{aligned}$$

Deci

$$A'_{ik} = \begin{vmatrix} 1 & -1 & 2 \\ -2 & 7 & 4 \\ 1 & 3 & 2 \end{vmatrix}$$

Componentele contravariante:

$$A'^{ik} = g^{il} g^{km} A_{lm},$$

deci avem nevoie de tensorul $g^{ik} = \vec{e}^i \cdot \vec{e}^k$, iar pentru aceasta trebuie să calculăm baza reciprocă.

$$\vec{e}^1 = -\frac{\vec{e}_2 \wedge \vec{e}_3}{\vec{e}_1(\vec{e}_2 \times \vec{e}_3)} = -\vec{i}_1 + \vec{i}_2;$$

$$\vec{e}^2 = \frac{\vec{e}_3 \times \vec{e}_1}{V} = -\vec{i}_1;$$

$$\vec{e}^3 = \frac{\vec{e}_1 \times \vec{e}_3}{V} = \vec{i}_3;$$

$$g^{ik} = \begin{pmatrix} 2 & 1 & 0 \\ 1 & 1 & 0 \\ 0 & 0 & 4 \end{pmatrix};$$

$$\begin{aligned} A'^{11} &= g^{11} g^{11} A_{11} + g^{11} g^{12} A_{12} + g^{11} g^{13} A_{13} + \\ &+ g^{12} g^{11} A_{21} + g^{12} g^{12} A_{22} + g^{12} g^{13} A_{23} + \\ &+ g^{13} g^{11} A_{31} + g^{13} g^{12} A_{32} + g^{13} g^{13} A_{33} = 11; \\ A'^{12} &= g^{11} g^{21} A_{11} + g^{11} g^{22} A_{12} + g^{11} g^{23} A_{13} + \\ &+ g^{12} g^{21} A_{21} + g^{12} g^{22} A_{22} + g^{12} g^{23} A_{23} + \\ &+ g^{13} g^{21} A_{31} + g^{13} g^{22} A_{32} + g^{13} g^{23} A_{33} = 10; \end{aligned}$$

etc...

$$A'^{ik} = \begin{pmatrix} 11 & 10 & 20 \\ 17 & 7 & 16 \\ 16 & 12 & 32 \end{pmatrix}$$

Penru componentele mixte

$$\begin{aligned} A'_k{}^i &= g^{ij} A_{jk}; \\ A'_1{}^1 &= g^{11} A_{11} + g^{12} A_{21} + g^{13} A_{31} = 5; \\ A'_2{}^1 &= g^{11} A_{12} + g^{12} A_{22} + g^{13} A_{32} = 7; \\ A'_3{}^1 &= g^{11} A_{13} + g^{12} A_{23} + g^{13} A_{33} = 5; \\ A'_1{}^2 &= 4; A'_2{}^2 = 4; A'_3{}^2 = 4; A'_1{}^3 = 4; A'_2{}^3 = 8; A'_3{}^3 = 8; \end{aligned}$$

$$A'^k{}_k = \begin{pmatrix} 5 & 7 & 5 \\ 4 & 4 & 4 \\ 4 & 8 & 8 \end{pmatrix}$$

La fel componentele $A'^k{}_l$.

4. Sunt dati vectorii de bază ai sistemului de coordonate $k(\vec{e}_1, \vec{e}_2, \vec{e}_3)$.

$$\left. \begin{aligned} \vec{e}_1 &= \vec{i}_1 + \vec{i}_2 \\ \vec{e}_2 &= 2\vec{i}_2 \\ \vec{e}_3 &= -\vec{i}_3 \end{aligned} \right\}$$

Componentele tensorului in sistemul $k(\vec{i}_1, \vec{i}_2, \vec{i}_3)$ sunt

$$A'^{ik} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 2 & 0 \\ 1 & 0 & 2 \end{pmatrix}$$

Calculati componentele covariante si contravariante in sistemul $k(\vec{e}_1, \vec{e}_2, \vec{e}_3)$.

Rezolvare (de sine stătător).